

# On Some Mixture Models and their Extreme Value Behavior

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- 1 Introduction
- 2 Three Mixture Distribution Models
- 3 MDA of Mixture Distributions
- 4 Infinite Mixture and Hazard Rate Functions
- 5 Numerical Examples

# 1. Introduction

- Finite Mixture: Distribution functions of failure times in lifetime data analysis and reliability engineering.

$$f(x|\Theta) = \sum_{i=1}^n c_i f_i(x|\theta_i)$$

- Linear Mixture: Completion times for jobs consisting of the parallel-processing of tasks

$$F^{(k)}(x) = \sum_{i=1}^k c_i F_i(x)$$

# Layer Model

- Layer Mixture: Modeling individual claim amounts covered by the ceding and reinsurance companies. For example, in an excess of loss contract with a limiting level (threshold),  $L$  and a retention level,  $M$ ,  $M \leq L$ , the amount,

$$W_i^c = \min(W_i, M) + \max(0, W_i - L)$$

covered by the cedent from each individual claim  $W_i$ ,  $i = 1, 2, \dots$ , with generic distribution  $F_W(x)$ , has a distribution function

$$F_{W^c}(x) = I_{\{x < M\}} F_W(x) + I_{\{M \leq x\}} F_W(L - M + x)$$

# Layer Model

- More general (re)insurance applications: Individual claim amounts  $X$  have a mixture distribution, i.e.

$X \sim F_1$  for  $X \geq u$ , claims below a threshold

$X \sim F_2$  for  $X < u$ , claims above a threshold

(C. Behrens, H. Lopes, and D. Gamerman, 2004)

## 2. Three Mixture Distribution Models

# Layer Mixture Distribution

**Definition** Given distributions  $\{F_i\}_{i=1,2,\dots}$  and thresholds  $0 = u_0 < u_1 < \dots$ , the layer mixture of the first  $k$  distributions denoted by  $F^{(k)}$  is defined recursively as

$$\overline{F^{(k)}}(x) = I_{\{x < u_{k-1}\}}(x) \overline{F^{(k-1)}}(x) + I_{\{x \geq u_{k-1}\}}(x) \overline{F^{(k-1)}}(u_{k-1}) \overline{F}_k(x - u_{k-1})$$

for any integer  $k > 1$  and  $F^{(1)}(x) = F_1(x)$ .



# Layer Mixture Distribution

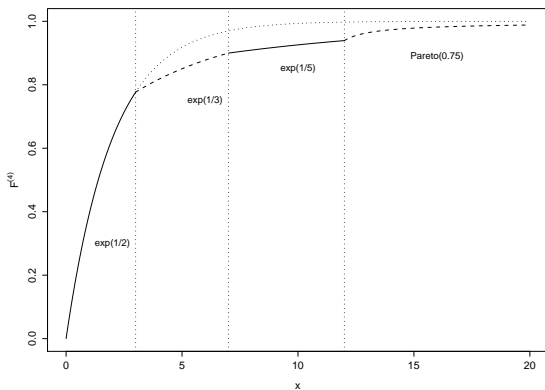


Figure: Layer Mixture

# Linear Mixture Distribution

**Definition** Given distributions  $\{F_i\}_{i=1,2,\dots}$ , the linear mixture of  $k$  distributions denoted by  $F^{(k)}$  is defined by

$$F^{(k)}(x) = \sum_{i=1}^k c_i F_i(x)$$

where  $c_i$  are negative or positive constants that sum to 1.

# Conditional Layer Mixture Distribution

**Definition** Given distributions  $\{F_i\}_{i=1,2,\dots}$  and thresholds  $0 = u_0 < u_1 < \dots$ , the conditional layer mixture of the first  $k$  distributions denoted by  $F^{(k)}$  is defined recursively as

$$\overline{F^{(k)}}(x) = I_{\{x < u_{k-1}\}}(x) \overline{F^{(k-1)}}(x) + I_{\{x \geq u_{k-1}\}}(x) \overline{F^{(k-1)}}(u_{k-1}) \overline{F}_k(x | x \geq u_{k-1})$$

for any integer  $k > 1$  and  $F^{(1)}(x) = F_1(x)$ .

# Conditional Layer Mixture Distribution

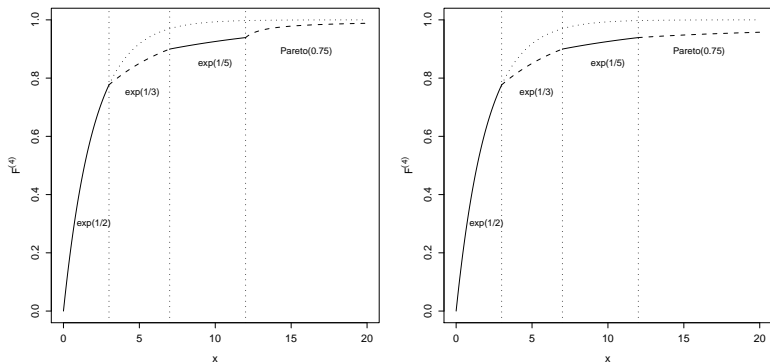


Figure: Layer Mixture vs. Conditional Layer Mixture

### 3. Maximum Domain of Attraction of Mixture Distributions

# MDA of Layer Mixture Distributions

Let  $F^{(k)}$  be a layer mixture distribution with distributional components  $F_i$  and thresholds  $0 = u_0 < u_1 < u_2 < \dots$  for a positive integer  $k > 1$ . If  $F_k \in MDA(H)$  for an extreme value distribution  $H$ , then  $F^{(k)} \in MDA(H)$  again and the normalizing constants are

$$\begin{cases} a_n = \gamma^{1/\alpha} a_n^*, & b_n = u_{k-1}, & \text{if } H \text{ is Fréchet,} \\ a_n = a_n^*, & b_n = b_n^* + u_{k-1} + a_n^* \log \gamma, & \text{if } H \text{ is Gumbel,} \\ a_n = \gamma^{-1/\alpha} a_n^*, & b_n = u_{k-1}, & \text{if } H \text{ is Weibull.} \end{cases}$$

where  $a_n^*$  and  $b_n^*$  are the normalizing constants of  $F_k(x)$ ,  $x_n^* = a_n^* x + b_n^*$ , and

$$\gamma = \prod_{i=1}^{k-1} r_i \quad \text{where} \quad r_i = \overline{F}_i(u_i - u_{i-1}).$$

# MDA of Linear Mixture Distributions

**Theorem(Kang and Serfozo, 1999)** Suppose that  $F^{(k)}$  is a linear mixture distribution and there exists a distribution  $F^*$  satisfying

$$\lim_{x \rightarrow \infty} \frac{\overline{F_i}(x)}{\overline{F^*}(x)} = r_i$$

for each  $i$ . Let  $\gamma = \sum_{i=1}^k c_i r_i$  and assume  $\gamma$  is positive. Then the following statements are equivalent.

1.  $F \in \text{MDA}(H)$
2.  $F^* \in \text{MDA}(H)$

# MDA of Conditional Layer Mixture Distributions

Let  $F^{(k)}$  be a conditional layer mixture distribution with distributional components  $\overline{F}_i$  and thresholds  $0 = u_0 < u_1 < u_2 < \dots$  for a positive integer  $k > 1$ . If  $F_k \in MDA(H)$  for an extreme value distribution  $H$ , then  $F^{(k)} \in MDA(H)$  again and the normalizing constants are

$$\begin{cases} a_n = \gamma^{1/\alpha} a_n^*, & b_n = 0, & \text{if } H \text{ is Fréchet,} \\ a_n = a_n^*, & b_n = b_n^* + a_n^* \log \gamma, & \text{if } H \text{ is Gumbel,} \\ a_n = \gamma^{-1/\alpha} a_n^*, & b_n = 0, & \text{if } H \text{ is Weibull.} \end{cases}$$

where  $a_n^*$  and  $b_n^*$  are the normalizing constants of  $F_k$ ,  $x_n^* = a_n^* x + b_n^*$ , and

$$\gamma = \prod_{i=1}^{k-1} r_i \quad \text{where} \quad r_i = \frac{\overline{F}_i(u_i)}{\overline{F}_{i+1}(u_i)}.$$



# Layer mixture is a linear mixture

**Theorem** The layer mixture distribution  $F^{(k)}$  can be written as a linear mixture of the form

$$F^{(k)}(x) = c_1 H_1(x) + \sum_{j=1}^{k-1} \sum_{i=2j}^{2j+1} c_i H_{i-j}(x) I_{\{u_j \leq x\}}(x)$$

where  $c_i = (-1)^{i-1}$  for  $i = 1, 2, \dots, 2k - 1$  and  $\overline{H}_i(x) = \overline{H}_{i-1}(u_{i-1}) \overline{F}_i(x - u_{i-1})$  for  $i = 2, 3, \dots, k$  and  $H_1 = F_1$ .

## 4. Infinite Mixture and Hazard Rate Functions

# Problems

- Threshold selection: Tail of  $F^{(k)}$  is explained by  $F_k$ , the last distributional component only.
  - Can we model the tail by a mixture distribution again? (by infinitely many thresholds and distributional components)
- Smooth mixture distribution: Jumps of hazard rate functions at  $u_i$  lead to non-differentiable mixture distribution.

# Hazard Rate Functions of Conditional Layer Mixture Distributions

Given distributions  $\{F_i\}_{i=1,2,\dots}$  and thresholds  $0 = u_0 < u_1 < \dots$ , let  $h_i$  be the hazard function of  $F_i$  for each  $i$ . Then the conditional mixture distribution  $F^{(k)}$  has the hazard function  $h^{(k)}$  which is the mixture of the first  $k$  hazard functions, i.e.

$$\overline{F^{(k)}}(x) = \exp\left(-\int_0^x h^{(k)}(s) ds\right)$$

where  $h^{(k)}$  is the simple mixture of the first  $k$  hazard functions such that

$$h^{(k)}(x) = \sum_{i=1}^{k-1} I_{\{u_{i-1} \leq x < u_i\}}(x) h_i(x) + I_{\{u_{k-1} \leq x\}}(x) h_k(x).$$

# Hazard Rate Functions of Conditional Layer Mixture Distributions

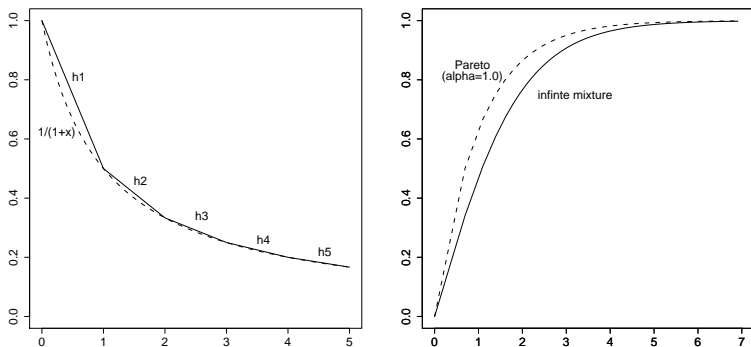


Figure: Mixture Hazard Function and Conditional Layer Mixture

# Infinite Conditional Layer Mixture Distributions

Given distributions  $\{F_i\}_{i=1,2,\dots}$  and thresholds  $0 = u_0 < u_1 < \dots$ , the infinite conditional layer mixture distribution denoted by  $\overline{F^{(\infty)}}$  is defined by

$$\overline{F^{(\infty)}}(x) = \sum_{i=1}^{\infty} I_{\{u_{i-1} \leq x < u_i\}}(x) \overline{F^{(i)}}(x)$$

or equivalently

$$\overline{F^{(\infty)}}(x) = \lim_{k \rightarrow \infty} \overline{F^{(k)}}(x)$$

where  $F^{(k)}$  is the conditional layer mixture of the first  $k$  distributions.

# Hazard Rate Functions of Infinite Mixture

Given distributions  $\{F_i\}_{i=1,2,\dots}$  and thresholds  $0 = u_0 < u_1 < \dots$ , the infinite conditional layer mixture distribution  $F^{(\infty)}$  has the mixture hazard function  $h^{(\infty)}$ , i.e.

$$\overline{F^{(\infty)}}(x) = \exp\left(-\int_0^x h^{(\infty)}(s) ds\right)$$

where  $h^{(\infty)}$  is the simple mixture of  $h_i$  such that

$$h^{(\infty)}(x) = \sum_{i=1}^{\infty} I_{\{u_{i-1} \leq x < u_i\}}(x) h_i(x),$$

# Limiting Distribution of Infinite Mixture

Let  $\delta = u_i - u_{i-1}$  for all  $i$  and consider a sequence of infinite mixture distributions  $F^{(\infty)}(x; \delta)$ . We are interested in the limiting distributions and limiting hazard functions as  $\delta \rightarrow 0$  such as

$$\lim_{\delta \rightarrow 0} F^{(\infty)}(x) \quad \text{and} \quad \lim_{\delta \rightarrow 0} h^{(\infty)}(x).$$



# Limiting Distribution of Infinite Mixture

**Theorem** Consider a sequence of thresholds  $u_0 < u_1 < \dots$  such that  $\delta = u_i - u_{i-1} > 0$  for all  $i$  and a sequence of distributions  $\{F_i(x; \delta)\}$  with hazard functions  $\{h_i(x; \delta)\}$ . If  $\lim_{\delta \rightarrow 0} h^{(\infty)}(x; \delta)$  exists and  $\lim_{\delta \rightarrow 0} F^{(\infty)}(x; \delta) < 1$ , then the hazard function of the limiting distribution  $F^{(\infty)}(x; \delta)$  is the limit of the mixture hazard function  $h^{(\infty)}(x; \delta)$  as  $\delta \rightarrow 0$ , i.e.

$$\lim_{\delta \rightarrow 0} \overline{F^{(\infty)}}(x; \delta) = \exp \left( - \int_0^x \lim_{\delta \rightarrow 0} h^{(\infty)}(s; \delta) ds \right).$$

Moreover, if the limiting hazard function is continuous, the limiting distribution is differentiable.

# Distributions of Limiting Hazard Functions

**Corollary** Any distribution  $F$  such that  $\overline{F}(x) > 0$  with a continuous hazard rate function  $h$  is a limiting distribution of the infinite conditional mixture of exponential distributions, i.e.

$$\overline{F}(x) = \lim_{\delta \rightarrow 0} \overline{F^{(\infty)}}(x; \delta)$$

where  $\overline{F}_i(x) = \exp(-h(u_i)x)$  for a sequence of thresholds  $u_0 < u_1 < \dots$  and  $\delta = u_{i+1} - u_i$ .

# Distributions of Limiting Hazard Functions

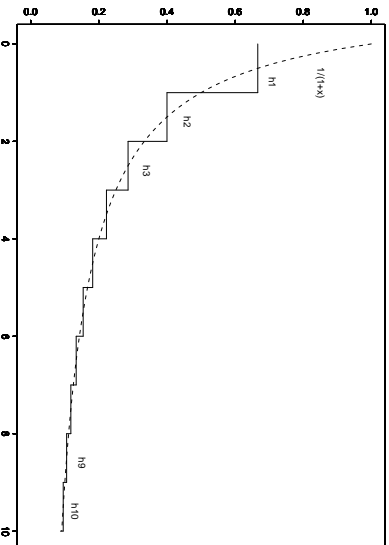


Figure: Pareto Hazard Function and Simple Function Approximation

## 5. Numerical Examples

# Danish Fire Loss Data

$d_i$  : number of losses in  $[u_{i-1}, u_i)$

$r_{i-1}$  : number of losses in  $[u_{i-1}, \infty)$

Empirical hazard rate function can be written as

$$\hat{h}(x) = \frac{d_i}{(u_i - u_{i-1})(r_{i-1} - \frac{1}{2}d_i)}, \quad x \in [u_{i-1}, u_i)$$

for each positive integer  $i$ , which leads us to identify the components of the mixture hazard function by  $\hat{h}$ , i.e.

$$\hat{h}_i(x) = \hat{h}(u_{i-1}), \quad \text{for } x \in [u_{i-1}, u_i)$$

## Danish Fire Loss Data

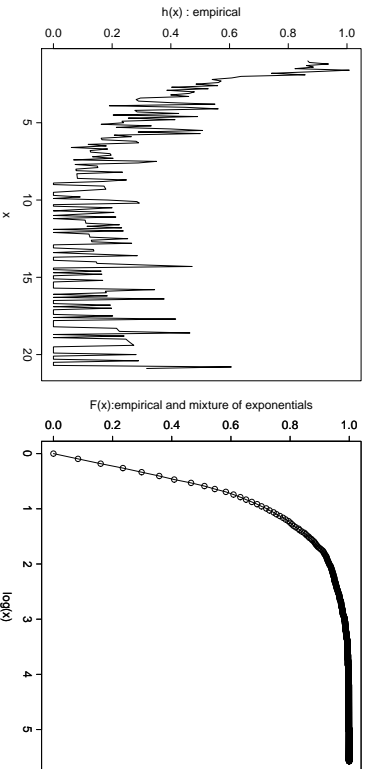


Figure: Empirical Hazard Function and Distribution Fit

## g-and-h Distributions

The g-and-h distribution with four parameters  $(a, b, g, h)$  can be defined as a transformation of the standard normal random variable  $Z$  such that

$$F(x) = Pr(X \leq x), \quad X = a + b \frac{e^{gZ} - 1}{g} e^{\frac{hZ^2}{2}}$$

where  $g$  and  $h$  can be real valued functions of  $Z^2$ .

(K. Dutta and J. Perry, 2004)

## g-and-h Distributions

$$(a, b, g, h) = (0, 1, 2.0, 0.2)$$

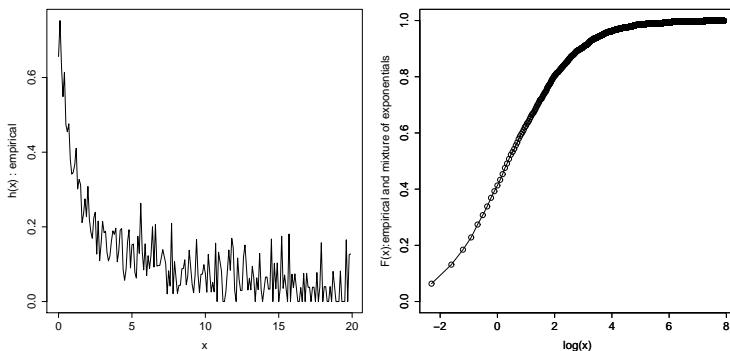


Figure: Empirical Hazard Function and Distribution Fit



# Key References

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